

$$RT_r(M) = \sum_{m_1, \dots, m_k=0}^{r-2} (-1)^{m_k + \sum_{i=1}^k a_i m_i} t^{\sum_{i=1}^k \frac{m_i(m_i+2)}{4}} [M_1+1]$$

$$\frac{k-1}{11} [(m_i+1)(m_{i+1}+1)] \langle e_{m_k} \rangle D(kp')$$

$$\langle e_m \rangle_{D(kp')}$$

$$= (-1)^m [M+1] \sum_{k=0}^m \sum_{l=0}^k (-1)^l t^{\frac{k(k+3)}{4}} + p' l(l+1)$$

$$\frac{\{k\}! \{2l+1\} \{m+k+1\}!}{\{k+l+1\} \{k-l\}! \{m-k\}!}$$

$$RT_r(M) = \sum_{m_1, \dots, m_k=0}^{r-2} \sum_{k=0}^{m_k} \sum_{l=0}^k (-1)^{\sum_{i=1}^k a_i m_i + k+l} t^{\sum_{i=1}^k \frac{a_i(m_i+2)}{4} - m_k(k+\frac{1}{2}) + p+\frac{1}{2}} l(l+1) + \frac{k(k+1)}{2}$$

$$[M_1+1] \frac{k-1}{11} [(m_i+1)(m_{i+1}+1)] \sin\left(\frac{2l+1}{r} 2\pi\right)$$

$$\frac{(t)_k (t)_{m_k+t+1}}{(t)_{k+t+1} (t)_{k-1} (t)_{m_k-k}}$$

$$\begin{aligned} & \sum_{i=1}^r m_i = m_i + 1 \\ & = \sum_{m_k=1}^{r-1} \sum_{k=0}^{m_k-1} \sum_{l=0}^k \left(\sum_{m_1 \dots m_{k-1} = 0}^{r-1} (-1)^{\sum_{i=1}^{k-1} a_i (m_i - 1)} \right. \\ & \quad \left. t^{\sum_{i=1}^{k-1} \frac{a_i (m_i^2 - 1)}{4}} [m_1] \prod_{i=1}^{k-1} [m_i m_{i+1}] \right) \end{aligned}$$

$$(-1)^{a_k(m_k-1) + k + l} t^{-(m_k-1) + (p' + \frac{1}{2})l} (t+1)^{\frac{k(k+1)}{2} + \frac{a_k m_k^2}{4}}$$

$$\frac{(t)_k (t)_{m_k+t+1}}{(t)_{k+t+1} (t)_{k-1} (t)_{m_k-k-1}} \sin\left(\frac{2(t+1)}{r} 2\pi\right)$$

$$\begin{aligned} & = \sum_{s=0}^{|g|-1} \sum_{m_k=1}^{r-1} \sum_{k=0}^{m_k-1} \sum_{l=0}^k \\ & \quad e^{\frac{-\pi J-1}{r} \frac{C_{k-1}}{g} (m_k + sr + \frac{k_{k-1} r}{2})^2} \cdot \sin\left(-\pi \frac{(y)^k}{8g}\right) \\ & \quad \left(2m_k + 2sr + \sum_{i=1}^{k-1} \frac{(y)^{i+1} k_i}{(i+1)} \right) \cdot \sin\left(\frac{2(t+1)}{r} 2\pi\right) \end{aligned}$$

$$\begin{aligned} & (-1)^{\frac{a_k m_k^2}{4} - m_k(k + \frac{1}{2}) + \frac{k(k+1)}{2} + (p' + \frac{1}{2})l} (t+1)^{m'} \\ & \quad m' = \frac{r}{2} - m_k \end{aligned}$$

$$= \sum_{s=0}^{|g|-1} \sum_{m'=-\frac{r-2}{2}}^{\frac{r-2}{2}} \sum_{l=0}^{\frac{r}{2}-m'-1}$$

$$\sin\left(\frac{2l+1}{r} \cdot 2\pi\right) \sin\left(\frac{x}{g} - J(s)\pi\right)$$

$$e^{\frac{2\pi i m'}{r}} + \frac{2\pi i J(2p+1)l}{r}$$

$$e^{\frac{r}{4\pi J-1}} V_r(x, y, z)$$

$$x = \frac{2\pi m'}{r}$$

$$y = \frac{2\pi k}{r}$$

$$z = \frac{2\pi l}{r}$$

$$V_r(x, y, z)$$

$$= -\frac{p}{g} x^2 + \frac{2\pi I(s)}{g} x + 4xy - 2\pi y - 2\pi z$$

$$-2y^2 + (-2-4p)z^2 + \varphi\left(\left[y + 2 + \frac{8\pi}{r} \right]\right)$$

$$+ \varphi\left(\left[y - 2 + \frac{\pi}{r} \right]\right) + \varphi\left(\left[\pi - x - y - \frac{\pi}{r} \right]\right)$$

$$-\varphi\left(\left[\pi-\lambda+y+\frac{\pi}{2}\right]\right)-\varphi\left[y+\frac{\pi}{2}\right]$$

$$\frac{\partial V_1(x,y,z)}{\partial z}$$

$$= -2\pi - 2(2-4p)z$$

$$-2\sqrt{1}\log(1-e^{2\sqrt{1}(y+2)})$$

$$+2\sqrt{1}\log(1-e^{2\sqrt{1}(y-2)})$$

whitehead link ;

$$\log w + \log x + \log y + \log z = 2\pi i$$

$$\log(1-w) + \log(1-x) - \log(1-y) - \log(1-z) = 0$$

$$\begin{matrix} m_1, & l_1, & m_2 & l_2 \\ \mu_1 & \nu_1 & \mu_2 & \nu_2 \end{matrix}$$

$$\mu_1 = \log(w-1) + \log(x) + \log(y) - \log(y-1)$$

$$-\pi i$$

$$V_1 = 2\log x + 2\log y - 2\pi i$$

$$\mu_2 = \log(w-1) + \log(x) + \log 2 - \log(2-1) - \pi i$$

$$V_2 = 2\log x + 2\log 2 - 2\pi i$$

$\mu_1 \hat{=} w, x, y.$

但 $\frac{\partial V}{\partial z}$ 只有两个变量, 看起来不能得出粘

点方程.